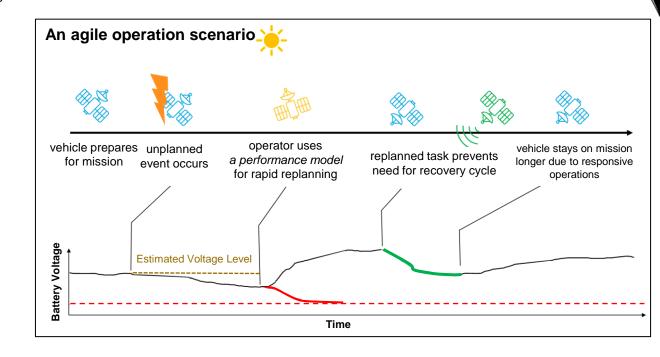


Motivation

The Need for Intelligent Energy Management in Space

- Space missions are becoming increasingly complex, driving the need for <u>agile</u> space operations
 - Requires real-time adaptation and optimization of spacecraft missions based on changing circumstances
 - Operators must be prepared to respond intelligently to unexpected events and make decisions
- Agile space operations could significantly impact EPS, particularly batteries, by introducing dynamic demands
- Examples include:
 - Maneuvering spacecraft to avoid space debris
 - Rapid reconfiguration of communication systems to handle varying data transmission needs

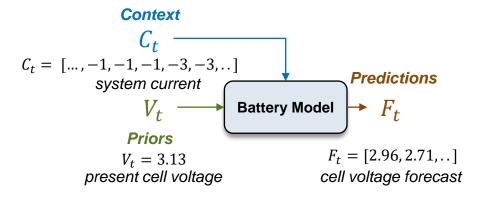


Agile space operations require real-time energy management solutions to handle unpredictable power demands

Battery Model Development Approach

Data-Driven and Physics-Informed Li-ion Battery Performance Modeling

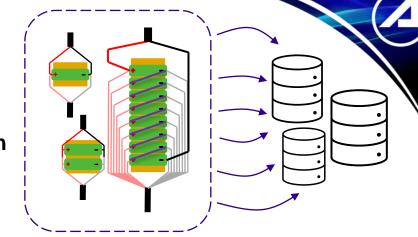
 To support agile scenarios, the goal of our battery model is to predict a forecast of future cell voltage given information about the present cell voltage and a context window of past and future current



$$F_t = f(C_t, V_t)$$

- Formulation
 - Model Inputs
 - Context of C_t = past and future system current, past voltage
 - Prior of p_t = **present cell voltage**
 - Model Outputs
 - Predict forecast of F_t = **future cell voltage**

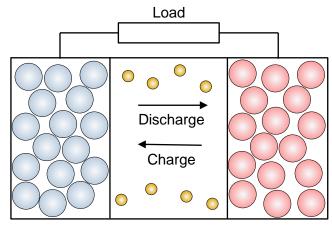
Data-driven Model



Big data No physics Some data
Some physics

Small data All physics

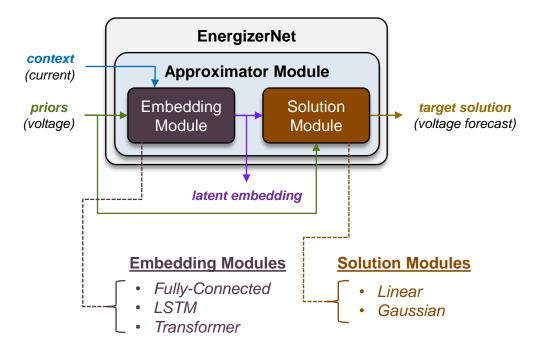
Physicsinformed Model



Anode Electrolyte Cathode

Data-Driven Model (EnergizerNet) Architecture

Embedding-Solution Modular Architecture



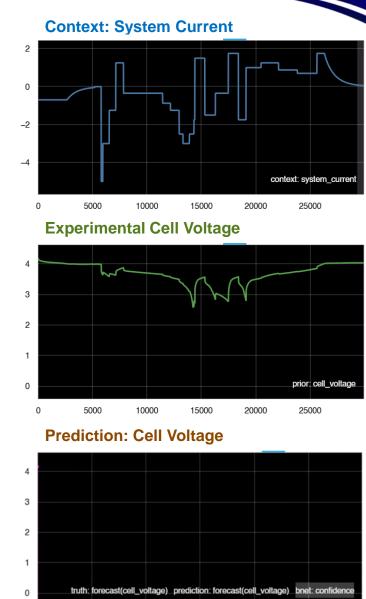
Data-driven model

input: prior cell voltage value and system current context window

output: forecast of future cell voltage values

Recursive Forecasting of Telemetry

Future prior voltages are estimated as a consensus of past voltage forecasts



5000

Time: 0

10000

20000

25000

A modular architecture that outputs both target solutions and latent embeddings of inputs

Data-Driven Model: Training Data Design Approach

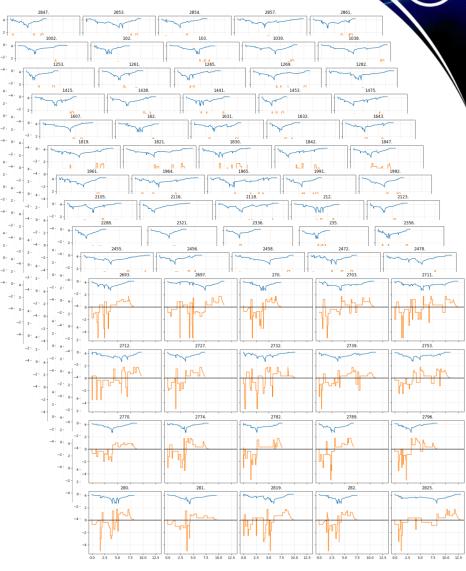
A model is only as good as its training data

Training data considerations:

 Most performance variability occurs at transitions (change in charge/discharge current)

Design approach:

- Hold as many conditions constant as possible to simplify the initial solution
 - SOH (assume BOL, limit test time on any individual cell)
 - Environment (generate all data at 20°C)
- 2. Create many combinations of the remaining variables to capture the bandwidth of performance
 - Current (vary charge/discharge current)
 - SOC (continue varying current over full capacity of cell)
- This design resulted in a matrix of [SOC, Current] pairs that were distributed over hundreds of "drive cycle"-style profiles.

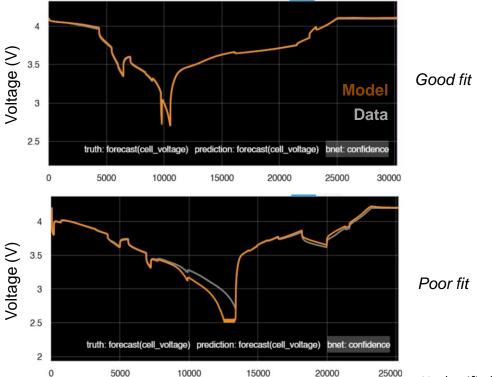


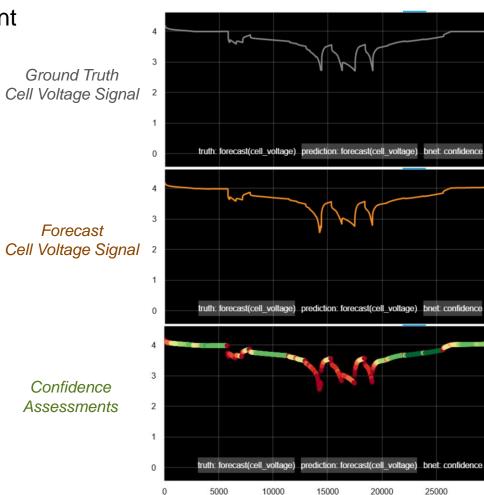
Generated a comprehensive dataset (850 drive cycles) using NMC-based Li-ion cells

Data-driven Model Results

Assessing Model Accuracy and Confidence

- Data-driven model predicts voltage responses given system current
- Quantifying confidence assessments
 - Enables operators to make informed decisions by highlighting areas where predictions are robust
 - Guides further data collection efforts to improve model accuracy in underrepresented regions

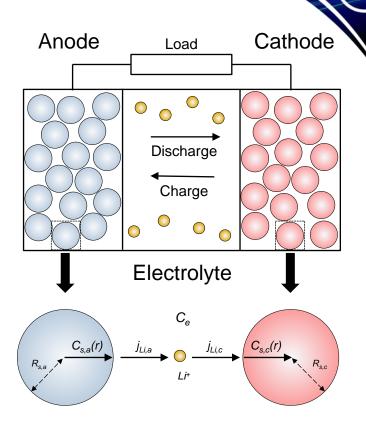




Physics-informed Model Background

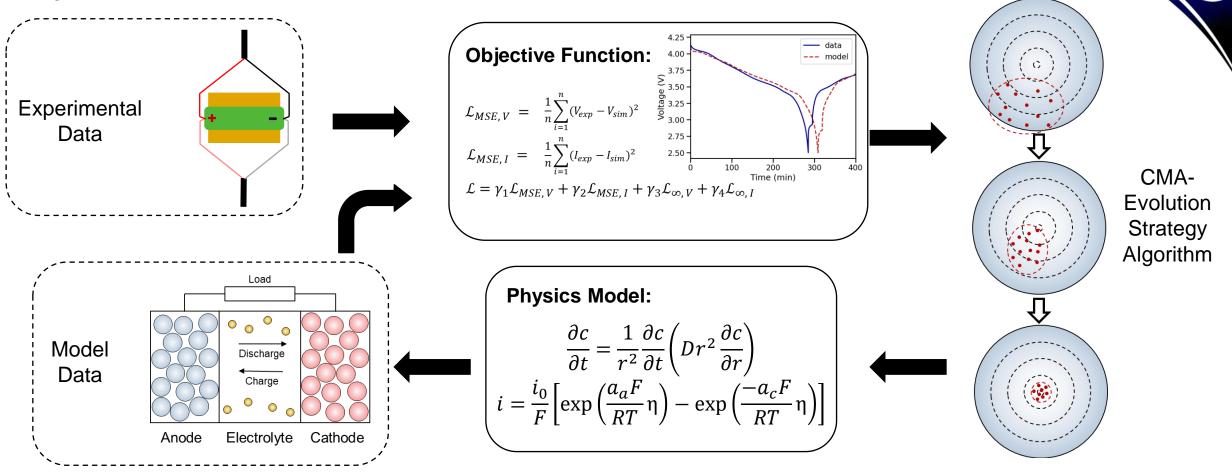
Integrating Physical Principles into Battery Modeling

- Our physics-informed model relies on a P2D (pseudo-two dimensional) approach
 - The P2D Li-ion cell model assumes radial symmetry and one-dimensional charge transport within the electrode materials
 - The parameters include electrochemical constants (diffusion coefficients, reaction rates), geometrical parameters (electrode thickness, active area), and thermodynamic properties
- Determining these parameters is challenging due to the complexity of electrochemical phenomena
 - It often requires requires both destructive and non-destructive, complex electrochemical experiments
 - This model involves a total of 23 physics-based parameters



The pseudo-2D battery model incorporates complex electrochemical parameters

Physics-informed Model Architecture



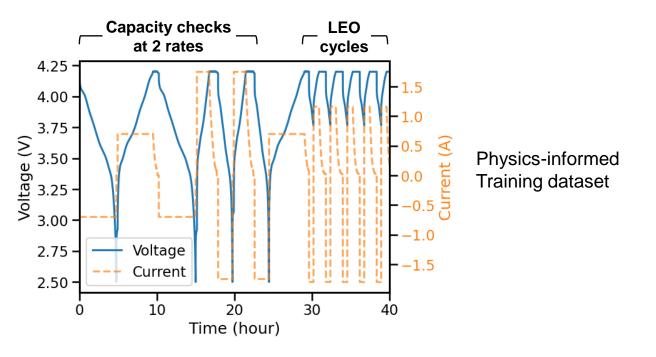
- Optimization algorithm iteratively adjusts model parameters by exploring the parameter space based on fitness evaluations
 - It utilizes gradient-free, covariance matrices to guide the search direction and accelerate convergence towards optimal parameters
- Goal is to minimize the difference between model predictions and experimental data (loss function)
 - Ensures that the model adheres to physical laws while fitting the data

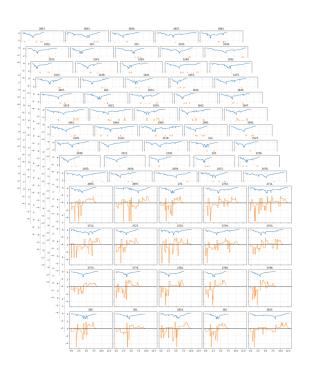
Physics-informed Model: Training Data Design Approach

Efficient Data Utilization for Physics-Informed Models

Training data considerations:

- The physics-informed approach incorporates fundamental electrochemical principles (needs OCV)
- Requires <u>significantly less training data</u> compared to data-driven approach (roughly 2 days vs 2 months)
- The training dataset consists of charge/discharge cycles at 2 different rates
 - Include a few Low Earth Orbit (LEO) cycles for realistic operational scenarios



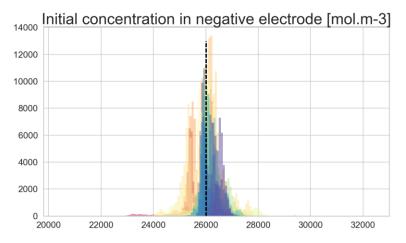


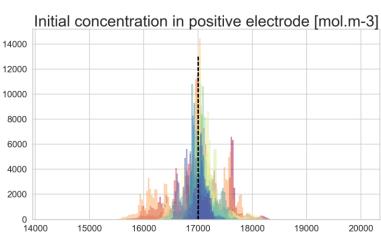
Data-driven model Training dataset

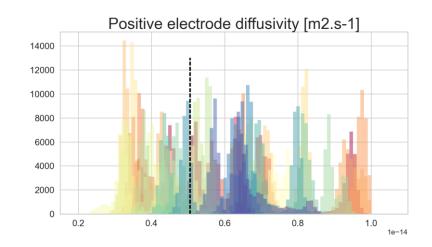
The physics-informed approach requires minimal data, focusing on key charge/discharge cycles to capture essential battery behaviors

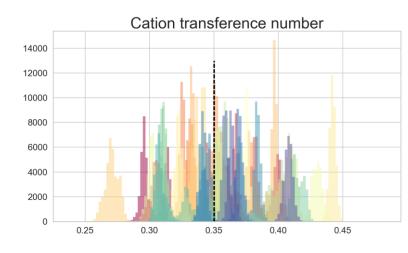
Physics-informed Model

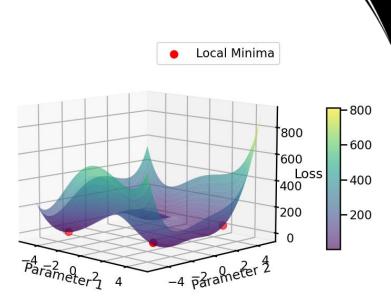
CMA-ES Optimization: Achieving Accurate Parameter Estimation











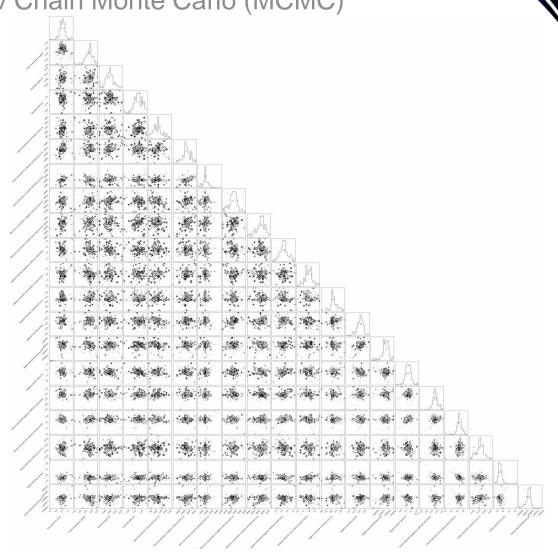
- Challenge of local minima due to a large number of model parameters
- Multiple parameter sets can yield similar loss values

Challenges of finding global optima due to high-dimensional parameter space

Physics-informed Model: Global Parameter Optimization Approach

ML Approach: Exploring Parameter Space with Markov Chain Monte Carlo (MCMC)

- MCMC methods simulate random walks through the parameter space of the physics-informed model
 - Applied Bayesian statistical modeling and probabilistic machine learning, in which unknown parameters are inferred in terms of their probability distributions
- Used for global sensitivity analysis to:
 - Identify key parameters affecting model performance
 - Quantify uncertainty in model predictions

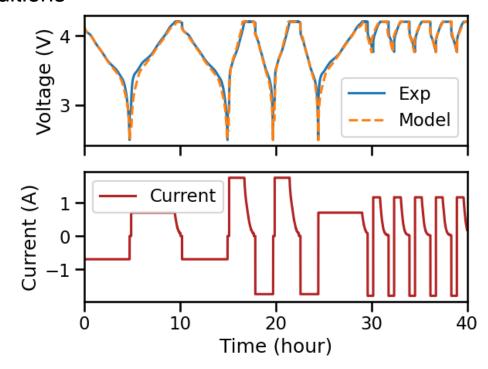


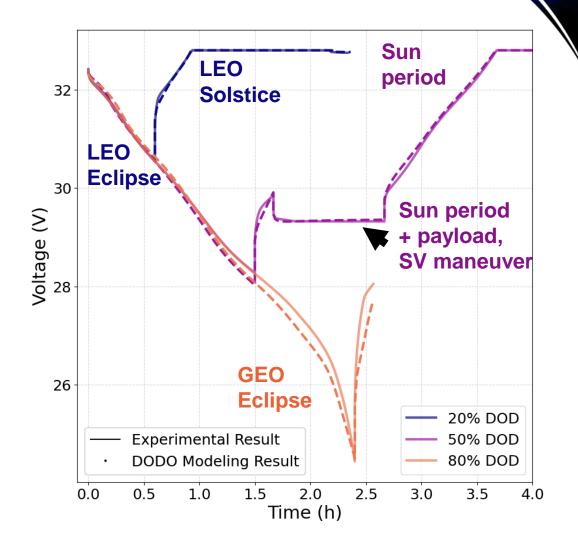
ML algorithm facilitate global sensitivity analysis, identifying key parameters and quantifying uncertainty

Physics-informed Model: Results

Validating Model Predictions

- Our model successfully predicted battery voltage with an average error of less than 42 mV.
- The physics-informed approach allows for predictions of battery performance/behavior under dynamic operating conditions





Our model demonstrates high-fidelity voltage predictions across various operational scenarios, validated against experimental data

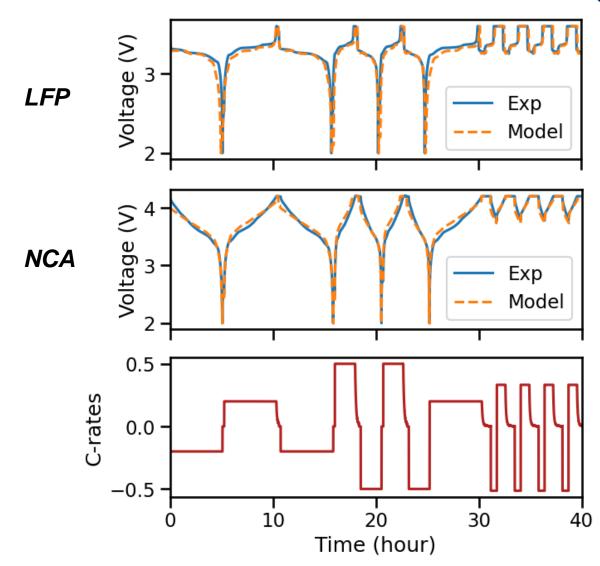
Application of Physics-Informed Model

Versatility Across Multiple Chemistries

- Applied the physics-informed model framework to LFP and NCA chemistries
 - Results show high accuracy in predicting voltage profiles for both chemistries
 - Demonstrates model's robustness and adaptability to different battery types
- An average training data error

- LFP: 51 mV

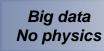
NCA: 56 mV



The physics-informed model accurately forecasts battery performance for both LFP and NCA chemistries

Summary: Comparison of Data-driven vs. Physics-informed Models

Evaluating Strengths and Limitations



Some data
Some physics

Small data All physics

- Data-driven Approach
 - − Pros
 - Leverage large datasets, adaptable to various scenarios, less dependent on detailed physical understanding
 - Cons X
 - Require extensive data for training, will likely struggle with extrapolation beyond training data

- Physics-informed Model
 - Pros <
 - Based on fundamental physical principles, require less data, robust to extrapolation, optimized model parameters are easily transferred, updated, and deployed
 - Cons X
 - Complex to develop (requires domain knowledge), parameter estimation can be challenging and computationally intensive

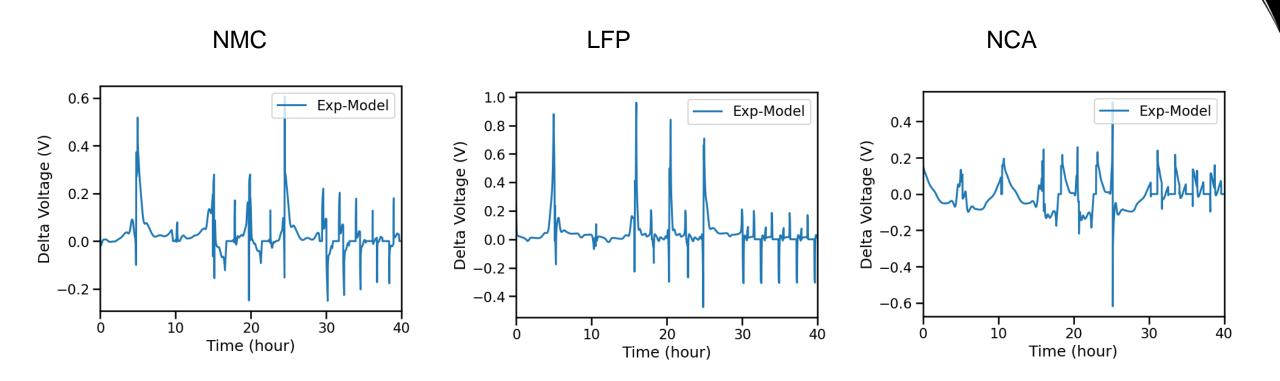




Physics-informed Model: Results



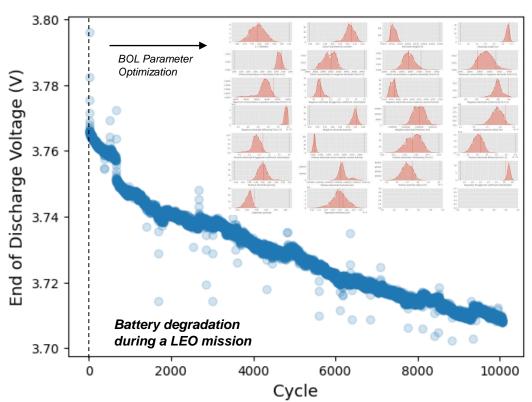
Difference between predicted and experimentally measured voltage profiles

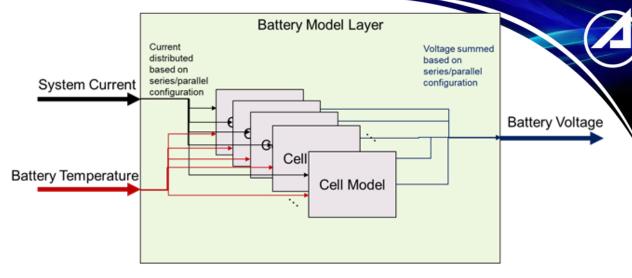


Physics-informed Model

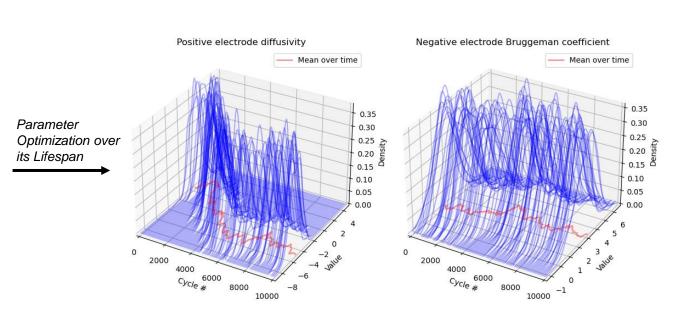
Future Work

- Battery-level model integration
- Long-term performance prediction





Space Battery Model Architecture



1

Optimizing the optimization: loss functions



MSE (Voltage)

$$\mathcal{L}_{MSE, V} = \frac{1}{n} \sum_{i=1}^{n} (V_{exp} - V_{sim})^2$$

MSE (Current)

$$\mathcal{L}_{MSE, I} = \frac{1}{n} \sum_{i=1}^{n} (I_{exp} - I_{sim})^2$$

L-Infinity norm (Voltage)

$$\mathcal{L}_{\infty, V} = |V|_{\infty} = max_i |V_{exp, i} - V_{sim, i}|$$

L-Infinity norm (Current)

$$\mathcal{L}_{\infty,I} = |I|_{\infty} = max_i |I_{exp,i} - I_{sim,i}|$$

Combined

$$\mathcal{L} = \gamma_1 \mathcal{L}_{MSE, V} + \gamma_2 \mathcal{L}_{MSE, I} + \gamma_3 \mathcal{L}_{\infty, V} + \gamma_4 \mathcal{L}_{\infty, I}$$