Toward Power Bus Standardization for NewSpace (2021 SPW - PMAD WORKSHOP)

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Power Standardization - Building Blocks for the Future

Discussion

- Common Interfaces are desired to reduce the cost & schedule, and risk involved when implementing the Electrical Power System Blocks:
 - Solar Array: Solar Cells, strings & arrays
 - Array Regulator: Convert the Array power to charge the Battery
 - Smart Battery: Li-Ion Cells, strings & packs, including protection, monitoring, & balancing
 - Power Distribution: Controlled delivery of energy to loads via resettable current limiters / breakers
 - Standardized I2C telemetry and command: Integral part of the Standard Block Interface
- Once qualified, multiple Vendors can produce each Plug & Play Block, similar to existing ACS and Communication gear
- Two standard block sizes of 100W and 500W increments are forecast to be easily "snapped together" to support 200W to 2,000W payloads for SmallSat missions
 - Parallel Blocks (module level) are utilized to provide increased robustness for power delivery
- Standardization is typically higher in size & weight, and lower in power efficiency
 - Trade off between standardization & point-design efficiency needs to be accepted by the community
 - What enablers and impediments exist in making a standardized EPS block-based system reality?

Standardization of EPS drives cost and schedules down, & increases robustness; SWaP is not the #1 goal

The Payload Customer is King, Queen, and Everything that Matters

Modularity allows standard power system blocks to be scaled for payload needs

- More focus from our Payload Customers on standard Bus systems (including power systems)
 - Customers looking toward the community for guidance in reducing Cost, Schedule & Risk
- Sole source procurements often drive schedule (and thus cost) by limiting choices
 - Customers want flexibility and options for working around schedule slips
- Spiral development of Payloads can require new / modified Bus subsystems to support changes
 - Increases in power consumption and ACS Control Authority often occur
- Launch vehicles drive space and weight allowability
 - Emphasis and focus on driving no volume (\bigcirc) massless (\bigcirc \bigcirc), perfect efficiency (\bigcirc \bigcirc \bigcirc) designs
 - Unobtanium of course but a goal
 - Standardization is somewhat contrarian to a point-design highly-efficient system

Standardization benefits include rapid response to Payload changing needs with modular blocks

Standards updates are needed for NewSpace

Robustness to accommodate standard designs using COTS

- Updated standards needed to consider lower "classical" reliability
 - Higher focus on shorter missions experimental (class D), demonstrations (class C), reliability at constellation level
 - Quicker understanding of failures, solutions, modification, and recovery
 - Drive quicker turn around from satellite concept to acquisition allows technology updates and reduced obsolescence
 - Some work done at Aerospace SmallSat Hub focus on considerations of design given classifications
 - Class C & D systems can quickly become real missions
- Example: Power standards update consideration
 - American Institute of Aeronautics and Astronautics (AIAA) "Electrical Power Systems for Unmanned Spacecraft" standard is outdated
 - Existing standards are not consistent with NewSpace model
 - Battery focus on outdated Ni-H2 based standards can drive PMAD in the wrong directions
 - High reliability focus not necessarily indicative of many of today's quicker, lower cost, but still reliable, missions
 - As we drive toward smaller spacecraft, margins, growth assessment may not be as applicable
- What work is in process toward standardization?
 - Not quite as much community focus relative to SmallSat standard considerations
 - Aerospace SmallSat Hub is doing some work in this area of the corporation is involved
 - Common ICD for Solar Array, Array Regulator, Smart Battery, Power Distribution, Standardized telemetry and command interfaces
 - Larger vehicle standard may be a starting point for SmallSat methodologies
 - Acquisition-based, from contract to SC design SMC and commercial focus as an example -needed for many SmallSat program offices

Updated standards with respect to Lithium battery based PMAD systems, & mission classification needed

Modification to Standards

Some Aerospace TOR work to modify existing standards

- Some Technical Operating Reports (TORs) exist and some are in progress which focus on NewSpace
- Lithium-Ion based & experimental/demonstration focused systems needs higher community focus with regard to standardization
 - ICD and few requirements driven + Lots of testing High focus on breadboarding and I&T program
- Standards can take multiple years to complete and can result in SmallSat standardization work becoming obsolete within a few years

Consideration for update standards with respect to Lithium battery based PMAD systems, & mission classification

Solar Array Module (minimum of two per S/V) Requirements



- Electrical Power: Two (+) and two (-) wired "loop" connections for redundancy
 - Open-circuit Voltage at Cold (-60°C) of 80V Maximum
 - Short-circuit Current at Hot (+100°C) of 2A (small) or 10A (Med) Minimum
 - Max Power Point at Operating Temperature (+60°C) of 40-60V
 - One Thermistor to report Array Temperatures

Battery Charger Module Interface Requirements



- Electrical Power: Two (+) and two (-) In & Out connections for redundancy
 - Battery charge Voltage Set-Point adjustable from 31V Minimum to 34V Maximum
 - Output Current of 3A (small) or 15A (Med) Minimum to provide 1C charge current to Battery
 - Eclipse Disable power-saver (NOTE: Array regulator is powered from S/A not Bus!)
 - Maximum Output Current Limiter set-point adjustable from Max to Max/2 Current
 - Charge Manager (Vsa Min, Veoc Max, Iout max) communications over I2C interface

Smart Battery Module Interface Requirements



- Electrical Power: Two (+) and two (-) connections for redundancy
 - Open-circuit fully charged Voltage of 33V Maximum
 - Discharge Current of 3A (small) or 15A (Med) Minimum for 1C nominal battery capability
 - Over- and under-Voltage disconnects to protect cells
 - Under-Temperature Charge Limiter at 0.1C to recover from dead-bus
 - Battery Cell Manager communications over I2C interface

Battery Discharger / Distribution Module Interface Requirements



- Electrical Power: Two (+) and two (-) In & Out connections for redundancy
 - Choice of Ideal Diode (Battery-on-Bus) or 34V Regulated Bus Voltage Modules
 - Regulated Voltage set at 34V; adjustable 33.8 to 34.2V for Load Balancing, or Active Droop
 - Output Current (100W, small) or (500W, Med) Minimum per parallel Module (2 minimum)
 - Load Manager (Vin, Vout, Iout) communications over I2C interface

Bus-to-Payload common Interface Standards are also in development



Bus-to-Payload Electrical Interface 04/02/2021 P. J. Carian

- **Electrical Power:** Fused parallel Power "Ring Bus" wires move the Main Bus from the Bus to the Payload with single-fault tolerance
 - A single connector provides Bus Power
 - Any single Short or Open wire will not impact P/L power delivery
- **C&DH:** Command, Telemetry and Data Interface sized and populated to meet P/L Requirements
 - Accommodation for two High-Speed Serial Buses (SRIO & SpaceWire)
 - Eight Basic LVDS signaling paths
 - Four Active & Four Passive P/L discrete
 TLMs with one common Return for each set
 - Standard Mil-38999 connectors specified

Defining the minimum set of electrical connections is a challenge, but agile Customers are demanding it

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It takes a village to raise our NewSpace Environment – Looking toward the future